

RECALL THE MAP $SO(2) \hookrightarrow SO(3)$
 INDUCES A HOM $\pi_1 SO(2) \rightarrow \pi_1 SO(3)$
 $\begin{array}{ccc} \parallel & & \parallel \\ \mathbb{Z} & & \mathbb{Z}/2 \end{array}$

$$SO(2) \approx S^1 = \text{CIRCLE}$$

$\pi_1 S^1 \hookrightarrow \text{WINDING } \#$
 $= \# \text{ OF TIMES A CLOSED PATH GOES AROUND } S^1$

TOPOLOGY OF $SO(3)$

DEF $\mathbb{RP}^n = \text{REAL PROJECTIVE } n\text{-SPACE}$

$:= \text{THE SET OF LINES THRU ORIGIN IN } \mathbb{R}^{n+1}$

TO TOPOLOGIZE THIS, LET

$U \subset \mathbb{R}^{n+1}$ BE ANY OPEN SET

AND LET $\tilde{U} \subset \mathbb{RP}^n$ BE THE SET OF LINES THRU 0 THAT ALSO INTERSECT U .

$\mathbb{RP}^n$ IS AN n -DIMENSIONAL SMOOTH MANIFOLD.

THERE IS A MAP

THERE IS A MAP

$$S^n \xrightarrow{p} \mathbb{RP}^n$$

IT IS A
DOUBLE
COVERING

SET OF UNIT
VECTORS IN $\mathbb{R}^{n+1}$

$\mathbb{RP}^0 = \text{POINT}$

$$\mathbb{RP}^1 \cong S^1$$

$$S^1 \xrightarrow{p} \mathbb{RP}^1$$

REMARK : FOR $n > 1$, $\pi_1 S^n = 0$

$$\text{AND } \pi_1(\mathbb{RP}^n) = \mathbb{Z}/2$$

IF $S^1 \xrightarrow{p} S^n$ IS NOT ONTO, LET
 $x \in S^n$ BE A POINT NOT
IN THE IMAGE

$$\begin{array}{ccc} S^1 & \xrightarrow{p} & S^n \\ & \searrow b' & \uparrow \\ & & S^n - \{x\} \cong \mathbb{R}^n \end{array}$$

AND b' IS HOMOTOPIC TO
THE CONSTANT MAP.

THEOREM $SO(3) \cong \mathbb{RP}^3$

LEMMA $\mathbb{RP}^n$ IS THE QUOTIENT

LEMMA RP^n IS THE QUOTIENT
OF D^n (n -DIMENSIONAL DISK)
OBTAINED BY IDENTIFYING
ANTIPODAL POINTS ON ITS
BOUNDARY $\partial D^n \cong S^{n-1}$

PROOF OF THEOREM. ANY POINT $\neq e$
IN $SO(3)$ CORRESPONDS TO
A ROTATION ABOUT SOME AXIS
COUNTERCLOCKWISE THRU SOME
ANGLE θ WITH $0 < \theta \leq \pi$

WE CAN DEFINE A MAP

$$D^3 \xrightarrow{\quad} SO(3)$$

||

$$\{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1\}$$

$$(0, 0, 0) \mapsto e \in SO(3)$$

OTHERWISE WE CAN WRITE

$$(x, y, z) = \mu \frac{(x, y, z)}{\mu} \quad \mu = \sqrt{x^2 + y^2 + z^2}$$

UNIT VECTOR
 λ

$f(x, y, z) =$ ROTATION ABOUT λ

$f(x, y, z) = \text{ROTATION ABOUT } \lambda$
WITH ANGLE $\pi/1$

NOTE THAT ANTIPODAL POINTS
ON $\mathbb{S}^3$ MAP TO THE
SAME ROTATION IN $SO(3)$

HENCE OUR MAP $\mathbb{S}^3 \rightarrow SO(3)$
FACTORS THRU $\mathbb{RP}^3$
LEADING TO THE DESIRED
HOMEOMORPHISM. QED

WE KNOW $SO(4) \cong SO(3) \times S^3$
 $\cong \mathbb{RP}^3 \times S^3$

IN GENERAL THERE IS A
MAP $SO(n) \xrightarrow{g} S^{n-1}$

$g := \text{EVALUATION AT SOME}$
 $\text{PRECHOSEN UNIT VECTOR}$
THE MAP IS ONTO.

$g^{-1}(\text{any pt}) \cong SO(n-1)$
DIFFERENT

THESE COPIES OF $SO(n-1)$ IN $SO(n)$ ARE DISJOINT SINCE EACH MAPS TO A POINT IN S^{n-1} .

SPECIAL FEATURE $n=4$: (AND $n=8$)
(AND $n=2$)
CAN USE QUATERNIONS TO
DEFINE A MAP

$$SO(4) \xrightarrow[h]{\theta} S^3 = \text{UNIT QUATERNIONS}$$

$$\exists h: S^3 \rightarrow SO(4) \text{ s.t. } gh = 1_{S^3}$$

CAN USE THIS TO SHOW

$$SO(4) = S^3 \times SO(3)$$

$$SO(8) = S^7 \times SO(7)$$

$$SO(2) = S^1 \times SO(1)$$

QUATERNIONS
(NOT COMM)

OCTONIONS OR
CAYLEY #1

(NOT ASSOC)

COMPLEX #1.

THERE IS NO 16-DIMENSIONAL
DIVISION ALGEBRA

THE COFFEE CUP + OTHERS TRICKS
ARE RELATED

THE COVERED UP POINTS ARE RELATED

$$SO(2) \longrightarrow SO(3)$$

$$\mathbb{Z} \cong \pi_1(SO(2)) \longrightarrow \pi_1(SO(3)) = \mathbb{Z}/2$$

$$2 \mapsto 0$$

CATEGORY THEORY

DEF A CATEGORY $\mathcal{C}$ CONSISTS OF

- 1) A COLLECTION OF OBJECTS
- 2) FOR ANY TWO OBJECTS X, Y A SET OF MORPHISMS

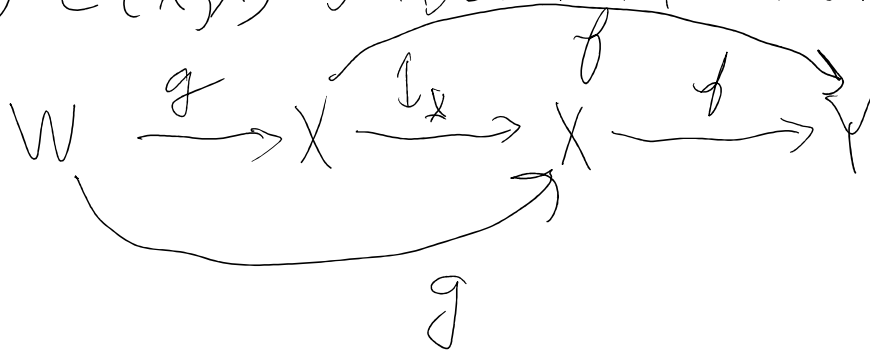
$$X \xrightarrow{f} Y \quad \mathcal{C}(X, Y)$$

- 3) GIVEN $X \xrightarrow{f} Y$ AND $Y \xrightarrow{g} Z$ THERE IS A COMPOSITE MORPHISM

$$X \xrightarrow{f} Y \xrightarrow{g} Z$$

COMPOSITION IS $g \circ f$ ASSOCIATIVE

4) $\mathcal{C}(X, X) \ni \text{IDENTITY MORPHISM}$



EXAMPLES

1) Set: OBJECTS ARE SETS
MORPHISMS ARE MAPS

2) Top: OBJECTS ARE TOP. SPACES
MORPHISMS ARE CONTINUOUS
MAPS

3) Grp: OBJECTS ARE GROUPS
MORPHISMS ARE
GROUP HOMOMORPHISM

4) WALKING
ARROW



EMPTY CAT
NO OBJECTS

5) ???



TRIVIAL CAT
ONE OBJECT
WITH IDENTITY

6) LET G BE A GROUP
 $\mathcal{C}_G = \text{CATEGORY WITH ONE OBJECT}$

THERE IS ONE MORPHISM FOR
EACH $\gamma \in G$ WITH COMPOSITION

EACH $\gamma \in G$ WITH COMPOSITION
GIVEN BY GROUP MULTIPLICATION.